

Innovative technologies to render your world.

ProRender

PRORENDER HYBRID RENDERING IN PRACTICE

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Agenda

- Requirements
- Hybrid engine modes
 - Raster
 - Hybrid
 - Biased path tracing
- Raytraced effects
 - Reflection / refraction
 - Ambient occlusion
 - Area lighting and shadowing
- Demo



Requirements

Radeon ProRender

- High quality unbiased path tracer
- Good at final rendering and complex scenes / materials
- Not that good at preview rendering and simple scenes / materials
- Noise
- High latency in an attempt to reduce variance as quick as possible
- Dynamic geometry

What to do?

- We need something fast and noise free for viewport / quick preview
- Realtime
- As accurate as possible given time budget
- Time budget differs for different GPUs models / generations



Hybrid engine

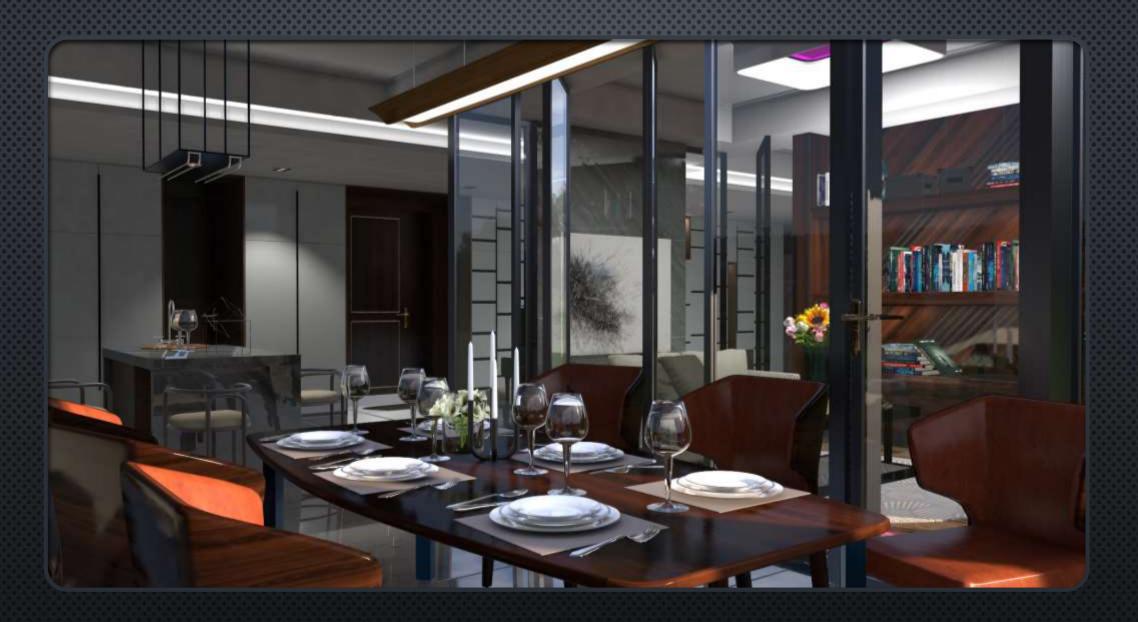
- Highly scalable rendering framework
 - Flexible and intuitive performance-quality tradeoff (game-like quality settings)
 - None to minimum amount of noise for all quality levels
 - Clever rendering spend time on complex things, fill the rest using ML or deterministic filters
 - Covers broad range of AMD hardware
- Flexible presets
 - High performance and high quality raster preview noise free
 - Hybrid ray-traced viewport noise free, deterministically filtered
 - Biased Monte-Carlo path tracer minimum noise, ML filtered
- Highly optimized for dynamic geometry / scene changes
 - Fast acceleration structure builds
 - Fast updates
 - Material / lighting changes



Hybrid engine

- Based on Vulkan 1.1
 - Works on any Vulkan 1.1 compatible hardware
 - Benefits from exclusive AMD hardware features:
 - Async compute
 - Shader ballot
 - Descriptor indexing
 - External memory
 - Spares resources
 - Uses RadeonRaysNext for ray casting





Radeon ProRender Building Blocks

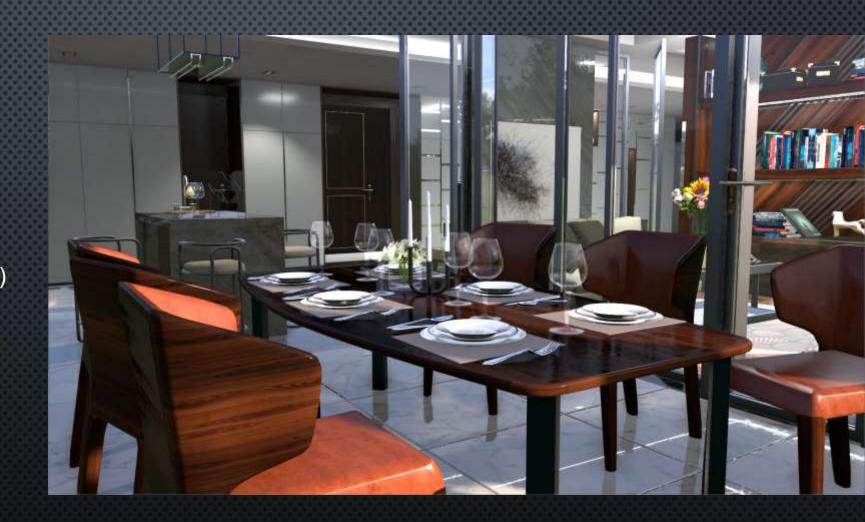
- Visibility solvers
 - Hardware rasterization
 - Ray tracing
 - Voxel ray tracing / cone tracing
- Illumination solvers
 - Approximate PBR (shadow maps, split sum)
 - Monte-Carlo path tracing
 - Voxel gather
 - Dynamic lightmaps
- Denoisers
 - Deterministic denoisers (EAW, SVGF)
 - ML denoising autoencoder
 - FidelityFX upscaler





Radeon ProRender Raster

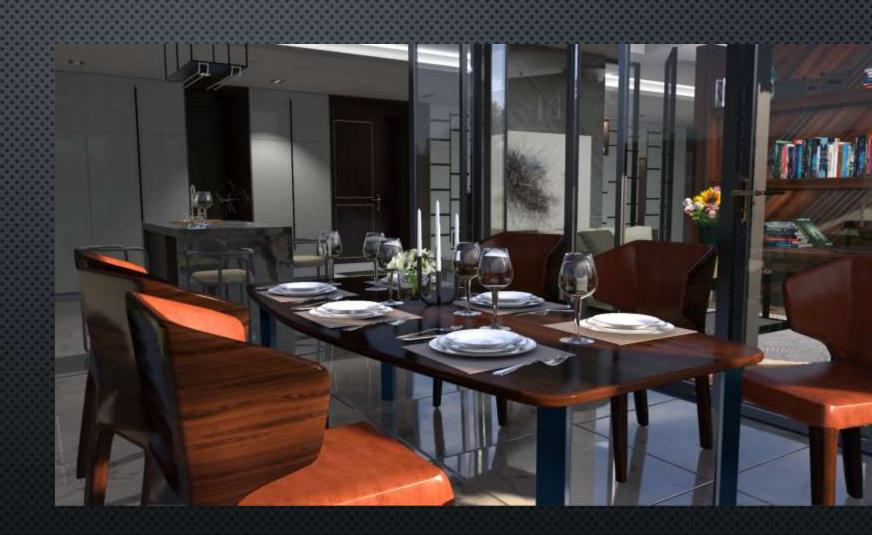
- Clustered deferred renderer
- Analytic and physical lights
- PBR uber material
 - GGX coating
 - GGX reflection
 - Lambert diffuse
 - Tranparency / refraction
- Reflections
 - Pre-computed IBL (split sum)
 - Screen space reflections
- Transparency
 - Weighted OIT
- . GI
 - Dynamic lightmaps
 - Voxel cone tracing
- TAA





Radeon ProRender Hybrid

- Thin visibility buffer
 - Depth
 - Normal
 - Texcoord
 - Barycentrics
 - Object ID
 - Material ID
 - Derivatives
- Reflections
 - Stochastic ray tracing
 - Multistage spatiotemporal denoiser
- Refraction
 - Ray tracing
- Area lighting
- . GI
 - Lightmaps
 - Voxel cone tracing





Radeon ProRender Path Tracer

- Wavefront path tracer
 - Based on RadeonRays
 - Aggressive compaction
- . GI
 - Full global illumination
 - Multiple importance sampling
 - Lightmaps
 - Voxels
- Denoise
 - DirectML based denoising autoencoder





Radeon ProRender: Reflections requirements

- GGX BRDF lobe
- Variable roughness support
- Can't trace more than 1spp at half resolution
- Need to preserve fine details



Radeon ProRender Usecase: Reflections

- Light transport equation
- F is a complex material function
 - IOR or metalness modes
 - Up to 2 reflection layers
- Denoise each layer separately
 - Use split-sum approx.
 - Precompute R * cos LUT
 - Calculate and denoise L at runtime

$$L(w_o) = \int_{\Omega} L_i(w_i) F(w_o, w_i) \cos \theta \, dw_i$$

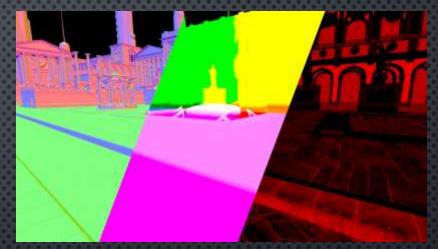
$$L(w_o) = \int_{\Omega} L_i(w_i)(C + R + D + RF) \cos \theta \, dw_i$$

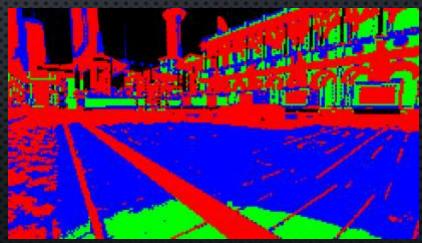
$$L_R(w_o) = \int_{\Omega} L_i(w_i) R(w_o, w_i) \cos \theta \ dw_i \approx$$

$$\int_{\Omega} L_i(w_i) dw_i \int_{\Omega} R(w_o, w_i) \cos \theta dw_i$$



- Rasterize primary visibility buffer:
 - Thin G-buffer: depth, normal, barycentrics, primitive ID, shape ID, derivatives
- Spawn rays from G-buffer:
 - Use reconstructed world space position, normal and GGX roughness
 - Use importance sampling using distribution of visible normal (Heitz 2014)
- Variable rate ray generation and shading:
 - Split G-buffer in tiles
 - Spawn different number of rays based on estimated reflection importance in a tile
 - Red: 1spp, blue: 1/4spp, green: 1/16 spp

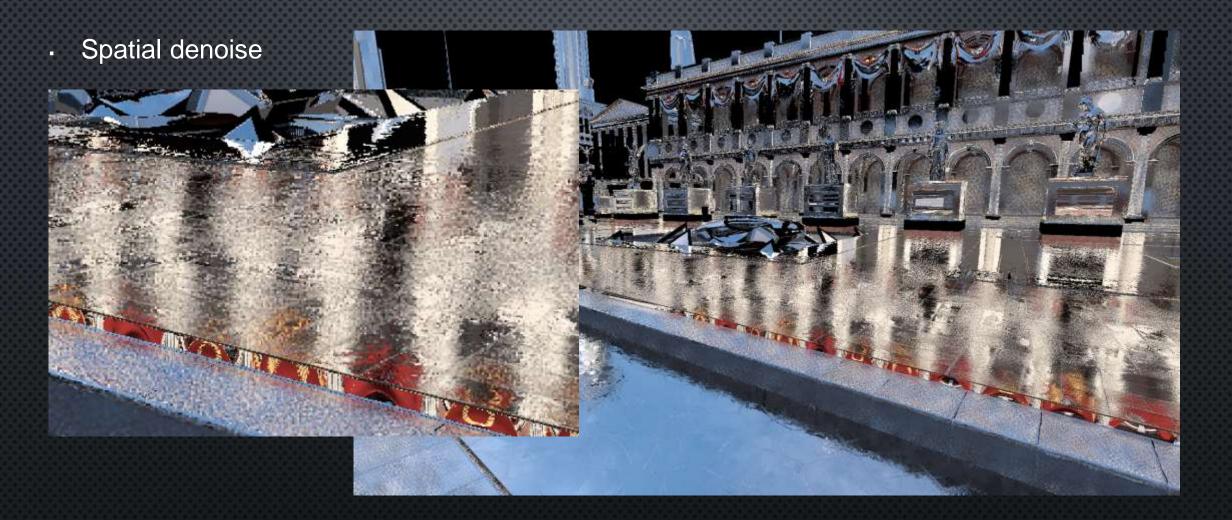


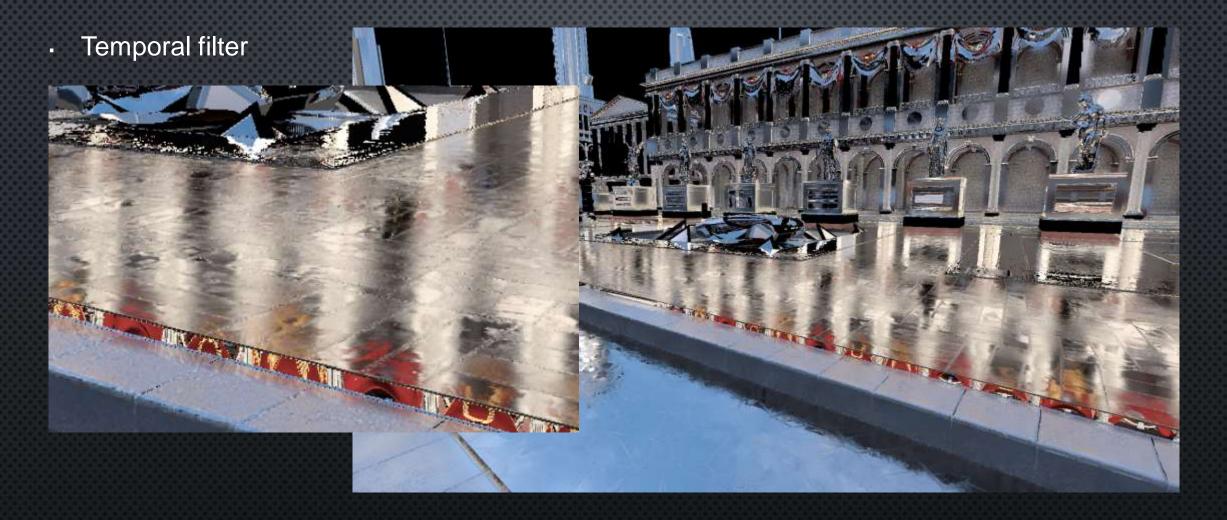


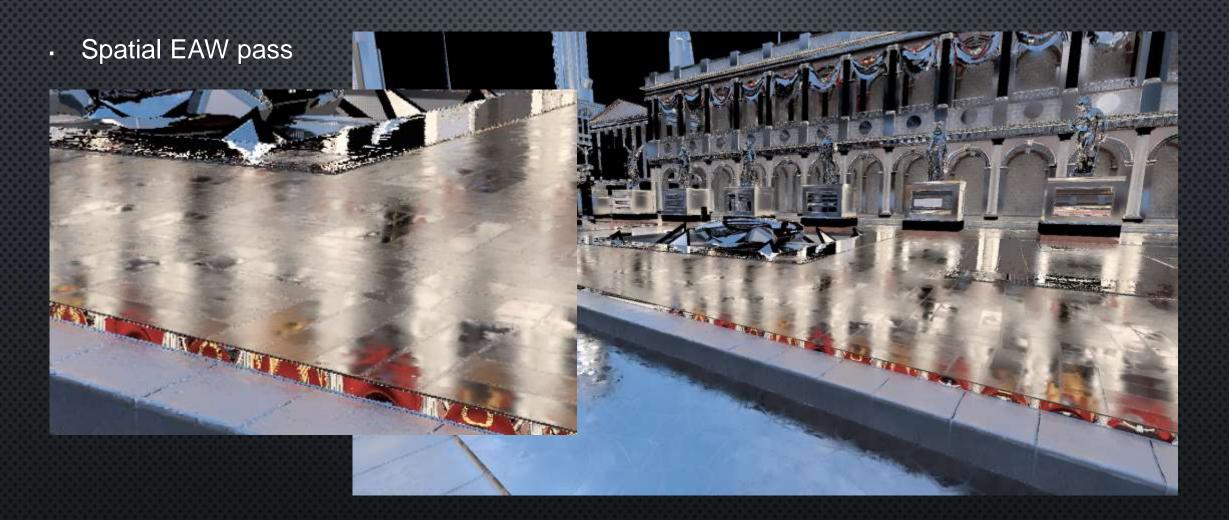




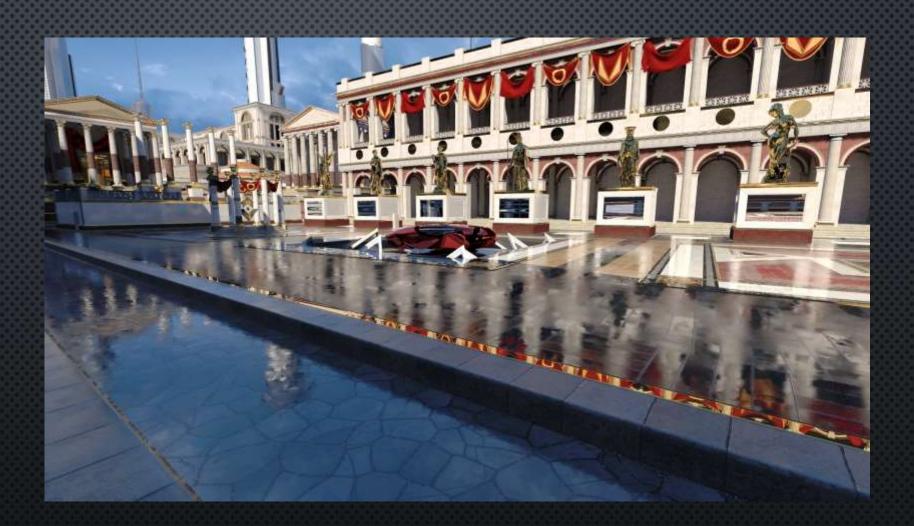








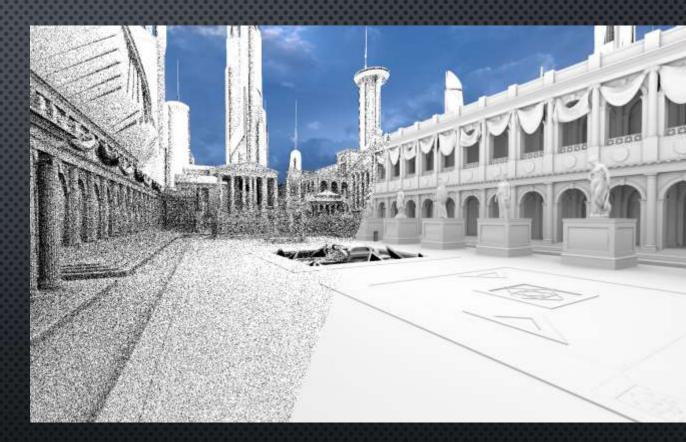
Final result





Radeon ProRender: Ambient occlusion

- Use cosine distribution to spawn1spp at half resolution
 - . Blue noise sampling
- Use occlusion query instead of a closest hit
- . Denoise result:
 - Reprojection
 - . Bilateral filter
 - . Temporal accumulation





Radeon ProRender: Area lighting and shadowing

Split area light integral into two parts:

$$L_{area}(\omega_o) = \int_A L_i(\omega_i) G(\omega_i) f(\omega_o, \omega_i) V(\omega_i) dA_i$$

$$\approx \int_A L_i(\omega_i) f_t(\omega_o, \omega_i) G(\omega_i) dA_i \int_A V(\omega_i) dA_i$$

- Use LTC (Heitz et al. 16) to compute lighting $\int_A L_i(\omega_i) f_t(\omega_o, \omega_i) G(\omega_i) dA_i$
- Use raytracing + denoising to compute visibility $\int_A V(\omega_i) dA_i$



Radeon ProRender: Area lighting and shadowing





Radeon ProRender: Reflections + AO + area lighting





Conclusion

- New Radeon ProRender backend
 - Vulkan 1.1
 - Performance-quality tradeoff
 - Optimized for AMD hardware
 - Cross platform
 - Cross vendor
 - Available for Blender 2.8+
- Visit

https://www.amd.com/en/technologi es/radeon-prorender-downloads

